

MarlinTPC

A Common Software Framework for TPC Development

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for the LC-TPC Collaboration



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MarlinTPC

A simulation, digitisation, reconstruction and analysis package for TPC development

Requirements for TPC R&D studies

- Geometry
 - Prototypes
 - Large collider detectors
- Simulation / Digitisation
 - Study detector effects
 - Realistic raw data
- Reconstruction
 - Stand alone (for prototypes: no track seed, no vertex constraint)
 - Various possible readout techniques
- Analysis
 - Ready-to-use standard analyses
 - Plots for prototype commissioning

⇒ MarlinTPC should be highly flexible and modular

LCIO: Linear Collider Input Output persistency framework

Event data model provides data classes

- Raw data
- 3D space points (hits)
- Tracks
- ...

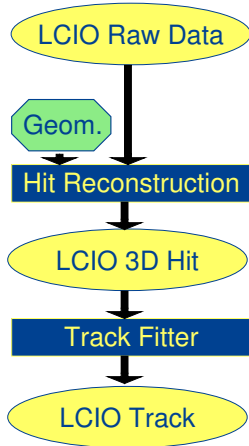
Marlin: Modular Analysis & Reconstruction for the Linear Collider

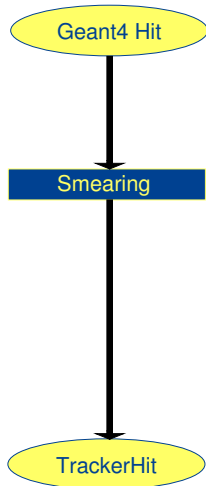
- Computing tasks implemented as so called *processors*
- LCIO data classes as input / output interfaces
- Steering files control data flow

GEAR: Geometry API for Reconstruction

API to programme against

⇒ code independent of specific detector implementation





- Detector response is implemented in "intelligent" smearing
- Fast (good for mass production)

Why is this not sufficient for detector R&D?

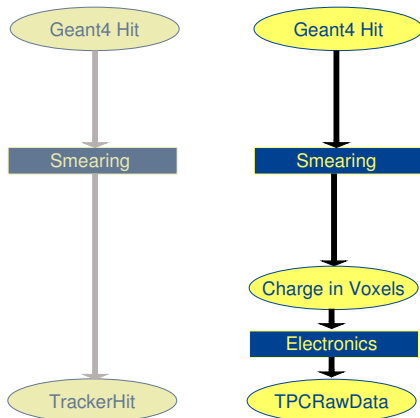
- Does not provide raw data (ADC counts on electronics channels)
- Completely skips pad geometry
- Skips major parts of the reconstruction
- No event pile-up
- Dead or noisy channels not included



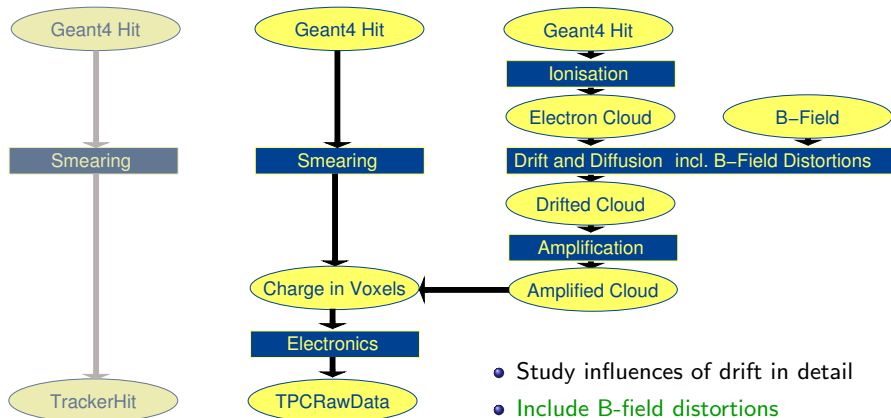
- TPC takes a long time to read out (\mathcal{O} 150 BX)
 - Electronics records many 2D pictures with readout frequency
- ⇒ 3D picture with *voxels*



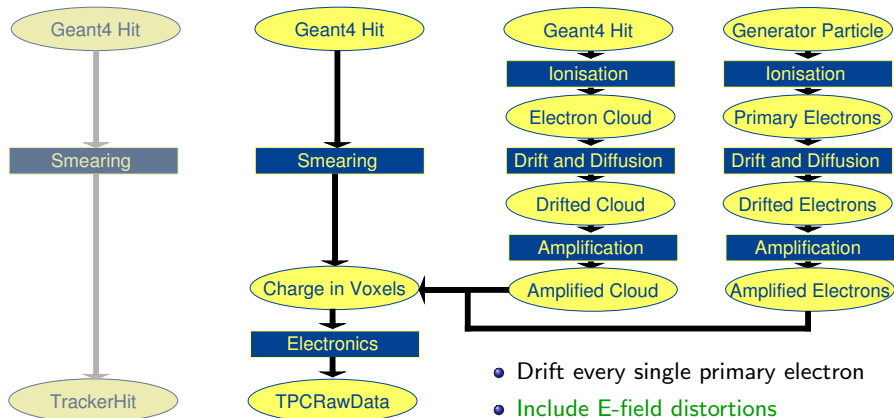
- TPC takes a long time to read out (\mathcal{O} 150 BX)
 - Electronics records many 2D pictures with readout frequency
- ⇒ 3D picture with *voxels*
- Tracks from multiple events simultaneously in the TPC
 - TPC makes one large 3D picture per **bunch train**
 - Matching with silicon tracker and calorimeter to determine BX



- Map of voxels resembles readout electronics
- Automatically implements event pile-up
- Background can be added
- Electronics specific converter provides realistic raw data



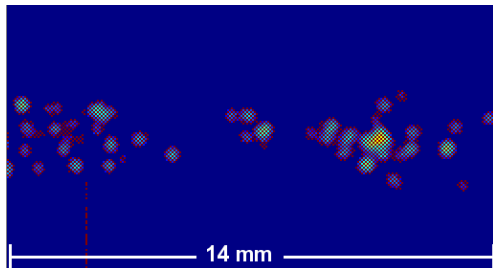
- Study influences of drift in detail
- Include B-field distortions
- Detailed simulation of gas amplification



- Drift every single primary electron
- **Include E-field distortions**
- Even more detailed simulation of gas amplification

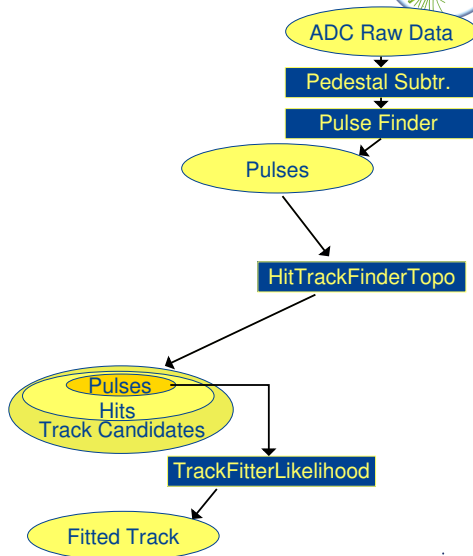
Why do we want to track every primary electron?

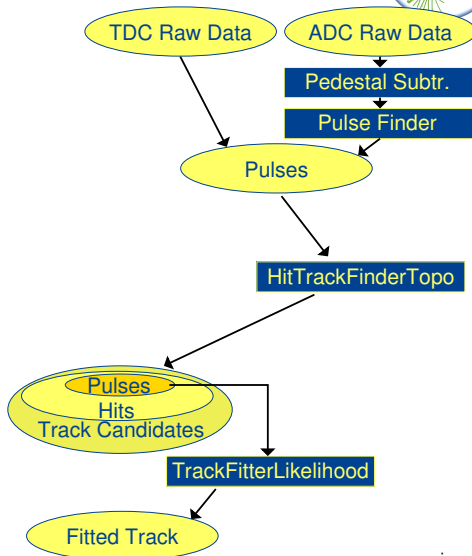
- TimePix Chip with $55 \times 55 \mu\text{m}^2$ pixels is able to resolve individual ionisation clusters and single electrons



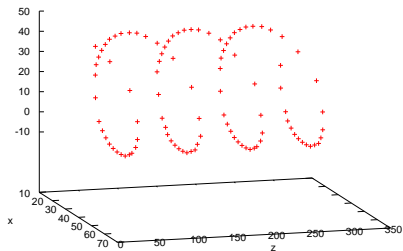
PixelMan Event Display

- Transfer coefficients in GEM readout are taken into account using binomial statistics
- Ion backdrift can be calculated



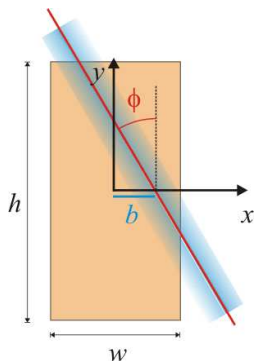






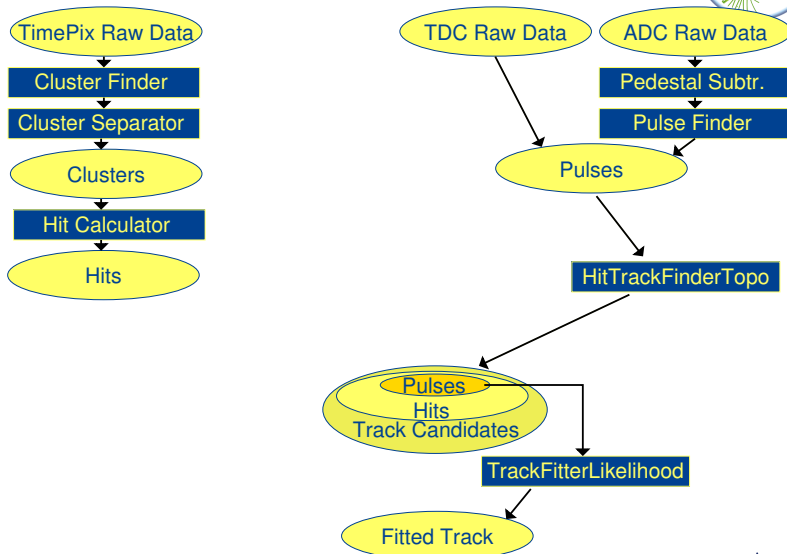
- Uses pulses on pads (pad geometry from GEAR)
- Searches for contiguous areas
- Independent of trajectory, no track hypothesis
- Works in 3D

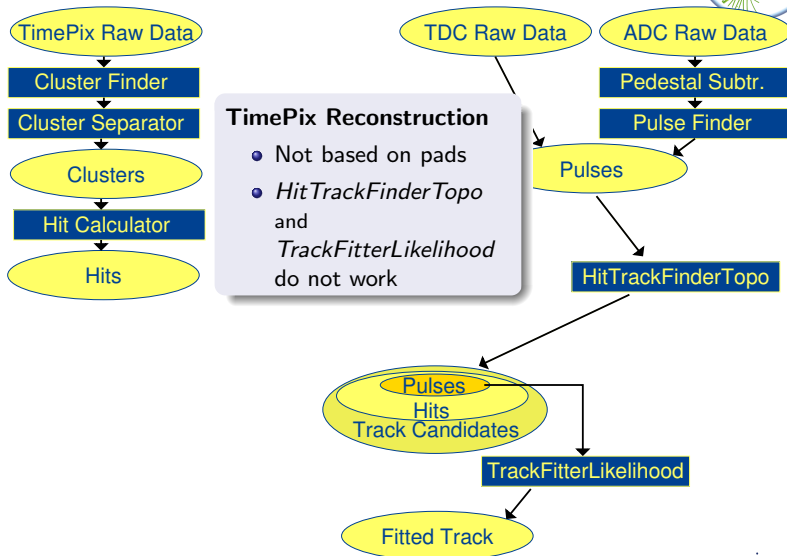
- The pad response can only be calculated correctly if angle of track wrt. pad row is known.
 - This cannot be done on hit basis
- ⇒ Do it globally for the whole track
- Calculate likelihood of charge distribution on a single pad row for given track parameters, assuming Gaussian distribution along the track
 - Sum up $\log(\text{likelihood})$ on all pad rows to get global likelihood
 - Maximise the $\log(\text{likelihood})$ by varying the track parameters

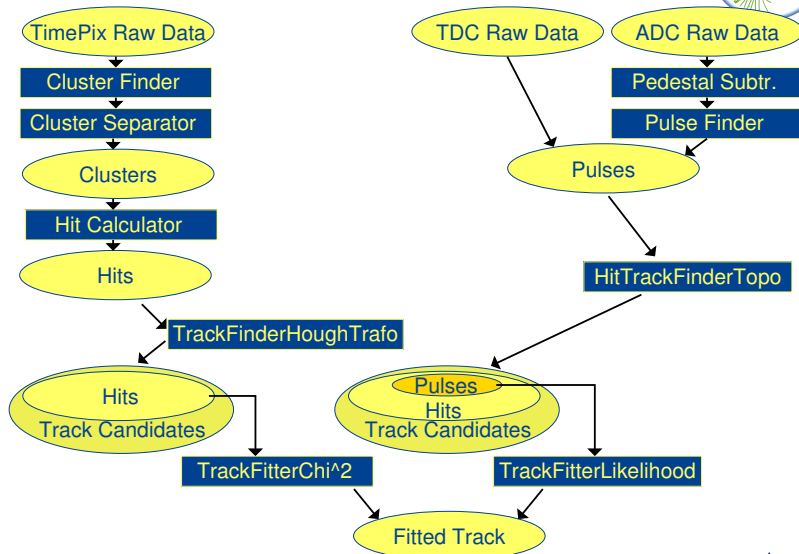


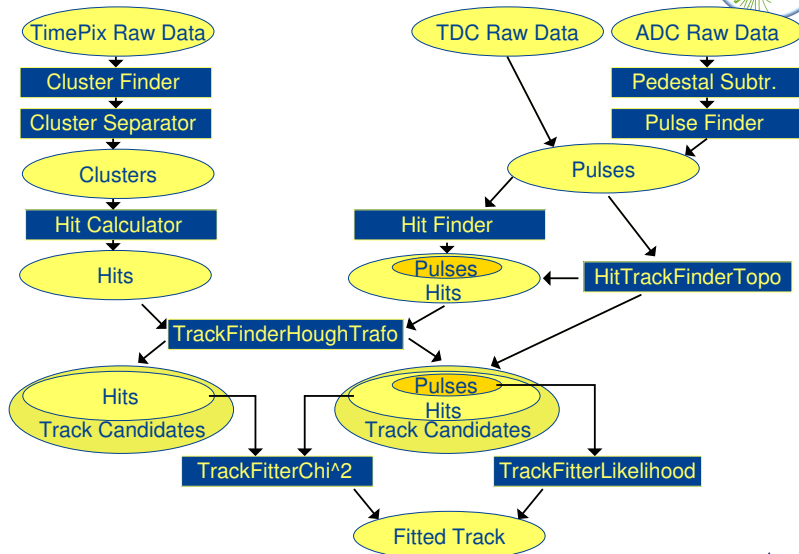
Implementation uses electron cloud drifter

⇒ Track fit includes field distortions









Requirements:

- Plots for detector commissioning
 - Occupancy diagrams
 - Efficiency histograms
 - Number of hits and tracks
 - ...
- Default analyses
(agreed on at the first LC-TPC Analysis Jamboree in 2006)
 - Residual distributions
 - Spatial resolution
 - Track parameters
 - Cluster sizes
 - ...

Example: Geometric-Mean Resolution

- Track fit with all hits (n fit) yields to small resolution values (biased estimator)
- Track fit without the test hit ($n - 1$ fit) yields too pessimistic values
- Geometric mean is an unbiased estimator

$$\sigma_{\text{Geo}} = \sqrt{\sigma_n \cdot \sigma_{n-1}}$$

MarlinTPC

- Highly modular
- Powerful digitisation
 - Realistic raw data
 - Realistic event pile-up
 - Fast branch and detailed branches
- Flexible reconstruction
 - Specialised and multi-purpose processors
 - Different kinds of readout

MarlinTPC is the default reconstruction and analysis tool for the joint LC-TPC Large Prototype test beam starting this autumn.

Next Steps:

- Data challenge:
Testing of all functionality with MC and prototype data
- Improve E- and B-field distortion corrections

Backup

